MIT COMPUTER SCIENCE AND ARTIFICIAL INTELLIGENCE LABORATORY



<u>September 14, 201</u>	<u>7 - Toyota Annual Review</u> 32-G449-Patil CSAIL	
8:30-9:00am	Arrival, breakfast	
9:00-9:10am	Welcome, introductions	
9:10-9:30am	TRI Perspective Gill Pratt, Chief Executive Officer, Toyota Research Institute	
9:30-9:50am	CSAIL Projects overview Daniela Rus, Director, CSAIL	
DRIVING		
9:50-10:05am	A Parallel Autonomous Driving System, Daniela Rus, Sertac Karaman Title: Parallel Autonomy with Dynamic Models and Probabilistic Path Envelopes Presenter: Daniela Rus	
10:05-10:20am	Decision Making for Parallel Autonomy in Clutter, Daniela Rus, Sertac Karaman Title: Decision Making Informed by Clutter and Verifiable Constraints Presenter: Daniela Rus	
10:20-10:35am	Tools and Data to Revolutionize Driving, Daniela Rus, Sertac Karaman Title: Learning and Control for Parallel Autonomy and Mapless Driving Presenter: Sertac Karaman	
10:35-10:50am	WiFi Based Obstacle Detection for Robot Navigation, Dina Katabi Title: Driverless Cars that See Through Fog Snow and Occlusions Presenter: Dina Katabi	
10:50-11:15am	BREAK	
11:15-11:30am	Driver-Friendly Bilateral Control for Suppressing Traffic Instabilities, Berthold Horn Title: Inverse Time-to-Contact as Proxy for Accident Probability Presenter: Berthold Horn	
11:30-11:45am	Geordi - A Driver's Assistant for Risk-Bounded Maneuvering, Brian Williams, Andreas Hofmann Title: A Driver's Assistant for Risk-Bounded Maneuvering Presenter: Andreas Hofmann	
	The Stata Center, Building 32-369	

32 Vassar Street, Cambridge, Massachusetts 02139-4307 РНОИЕ +1.617.253.0145 weв csail.mit.edu

11:45-12:00pm	Uhura - A Driver's Personal Coach for Managing Risk, Brian Williams, Tiago Stegun Vaquero
	Title: Uhura - A Driver's Personal Coach for Managing Risk Presenter: Andreas Hofmann
12:00-1:00pm	LUNCHEON- Star Seminar Room 32-D463
	PERCEPTION - LANGUAGE
1:00-1:15pm	Uncovering the Pain Points in Driving: Ruth Rosenholtz, Fredo Durand, Bill Freeman, Aude Oliva, Antonio Torralba Title: Understanding the Road and Understanding the Driver Presenter: Bill Freeman
1:15-1:30pm	Crossing the Vision-Language Boundary for Contextual Human-Vehicle Interaction: Jim Glass Title: Crossing the Speech/Vision Boundary Presenter: Jim Glass
1:30-1:45pm	Drinking from the Visual Firehose: High-Frame-Rate, High-Resolution Computer Vision for Autonomous and Assisted Driving: Saman Amarasinghe, Fredo Durand Title: TACO Tensor Algebra Compiler Presenter: Saman Amarasinghe
1:45-2:00pm	Using Vision and Language to Read Minds: Nick Roy, Boris Katz Title: Language Understanding with Accrued Visual-Linguistic Context Presenter: Nick Roy
2:00-2:15pm	Predicting a Driver's State-of-Mind: Antonio Torralba, Wojciech Matusik Title: Predicting a Driver's State of Mind Presenter: Wojciech Matusik
2:15-2:30pm	Exploring the World of High Definition Touch: Ted Adelson Title: Exploring the World of High Definition Touch Presenter: Ted Adelson
	VERIFICATION - VALIDATION
2:30-2:45pm	Formal Verification Meets Big Data Intelligence to Address the Trillion Miles Challenge: Armando Solar-Lezama Title: Formal Verification Meets Big Data Intelligence to Address the Trillion Miles Challenge Presenter: Armando Solar-Lezama
2:45-3:00pm	The Car Can Explain: Gerry Sussman, Hal Abelson, Lalana Kagal, Daniel Weitzner Title: When Things Go Wrong Presenter: Gerald Jay Sussman

3:00-3:20pm	BREAK
3:20-3:35pm	Simulation and Verification for Vision-in-the-Loop Control: Fredo Durand, Aleksandar Zlateski Title: Computer Graphics for Perception and Learning Presenter: Fredo Durand
3:35-3:50pm	Analysis by Synthesis Revisited: Visual Scene Understanding by Integrating Probabilistic Programs and Deep Learning, Josh Tenenbaum Title: Visual Scene Understanding by Integrating Probabilistic Programs and Deep Learning Presenter: Josh Tenebaum
3:50-4:15pm	Wrap-up Discussion
4:15-5:30pm	Reception with Demos and Poster Session - R&D Commons and Star

5:00-6:00pm SAB will be meeting in Bleil 32-G601

